

Reeti ROS API

- [Reeti Ros Node](#)
- [Use Ros from a remote computer](#)
- [Ros Samples](#)

For Reeti V2

- ROS Indigo is installed by default
- add ROS dev directory to the path: add the following two lines at the end of the file */home/reeti/.bashrc*:

```
source /opt/ros/indigo/setup.bash
export ROS_PACKAGE_PATH=$ROS_PACKAGE_PATH:/home/reeti/reetiDevel/Samples/ROS
```

- restart any open terminals to make sure you use the new *.bashrc*
- refer to [ROS Samples](#) and [Reeti ROS Node](#) documentation.

For Reeti V1

- Install ROS : <http://www.ros.org/wiki/fuerte/Installation/Ubuntu>
- add ROS dev directory to the path: add the following two lines at the end of the file */home/reeti/.bashrc*:

```
source /opt/ros/fuerte/setup.bash
export ROS_PACKAGE_PATH=$ROS_PACKAGE_PATH:/home/reeti/Devel/Samples/ROS
```

- restart any open terminals to make sure you use the new *.bashrc*
- refer to [Ros Samples](#)

Remarks :

- the first time you compile a ROS application, *roscpp* will ask you to execute "*sudo rosdep init*" then "*rosdep update*"